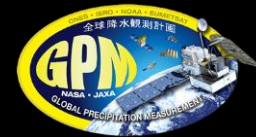




Ground Validation Assessments of GPM Core Observatory Science Requirements



Walt Petersen, NASA-MSFC

George Huffman, NASA-GSFC, Chris Kidd, U. Maryland; Gail Skofronick-Jackson, NASA-GSFC



Outline

- "Level-1" Science Requirements
- Data
- Rain rate
- DSD
- Demonstrating Snow Detection
- Summary

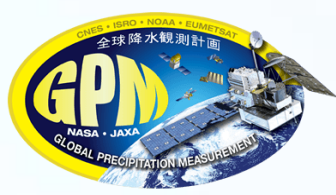
Acknowledgements:

P. Kirstetter, D. Wolff, D. Marks, K. Morris, T. Berendes, V. Chandrasekar, M. Schwaller, J. Tan



GPM “Core” Satellite Science Requirements

(Termed “Level -1” or “L1”)

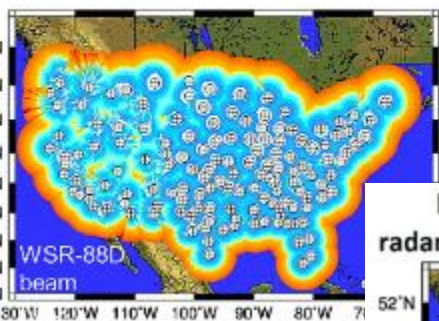
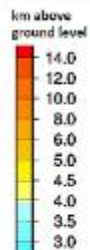


- DPR: *quantify rain rates* between 0.22 and 110 mm hr⁻¹ and *demonstrate the detection of snowfall* at an *effective resolution of 5 km*.
- GMI: *quantify rain rates* between 0.22 and 60 mm hr⁻¹ and *demonstrate the detection of snowfall* at an *effective resolution of 15 km*.
- Core observatory radar estimation of the Drop Size Distribution (DSD)- specifically, *D_m to within +/- 0.5 mm*.
- At 50 km resolution, space-based *instantaneous* rain rate estimate with *bias and random error < 50% at 1 mm hr⁻¹ and < 25% at 10 mm hr⁻¹, relative to calibrated GV*

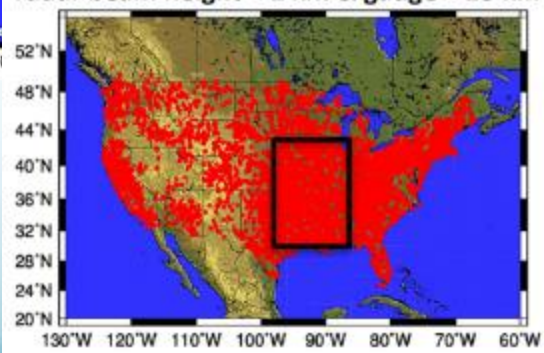
1) NOAA Multi-Radar Multi-Sensor (MRMS) Precipitation Rates

- Gauge bias-corrected radar estimates of precip **rate and type**
- 0.01° / 2 minute resolution
- Quality-constrained "reference" subsets created

MRMS Radar Beam Height

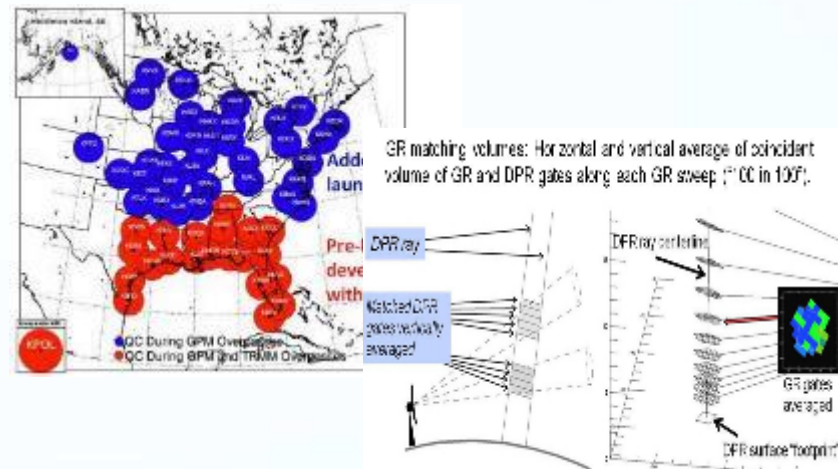


MRMS best observation areas
radar beam height < 2 km & gauge < 25 km



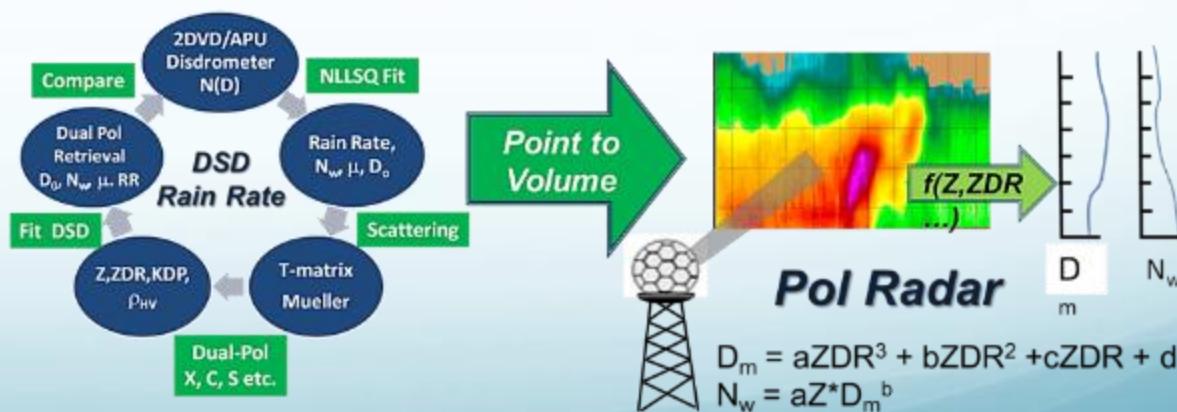
2) Validation Network

- QC'd 3-D radar volumes and variables geo-matched to DPR sample volumes and GMI footprints
- 65 US + numerous research and international radars



3) Field site observations

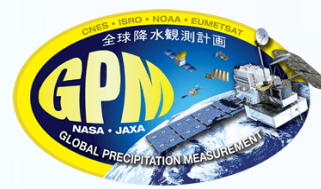
- Disdrometer, Radar, Dense Gauge network



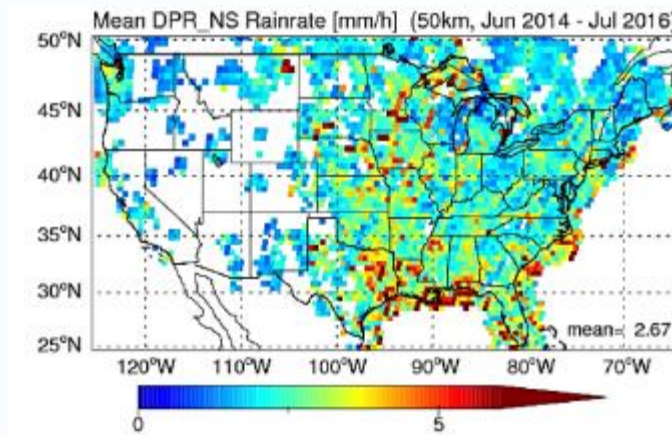


Rain: General Continental Context (50 x 50 km)

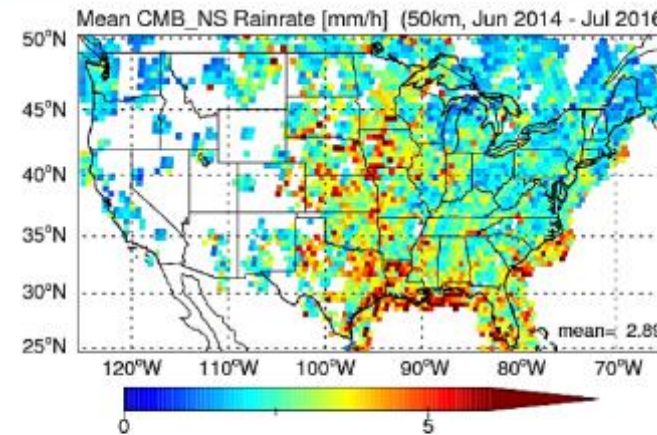
CONUS June 14 – July 16: GV MRMS vs. DPR, Combined, and GMI GPROF
Conditioned on 0.2 mm/hr threshold at FOV



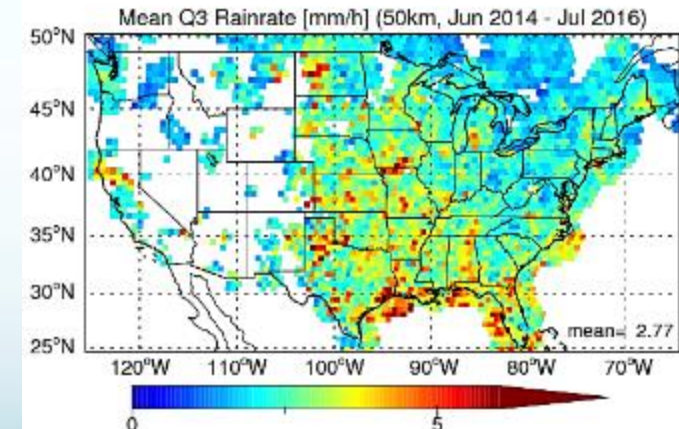
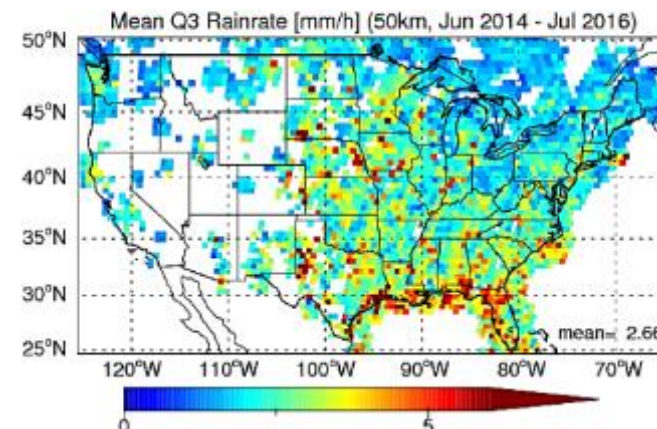
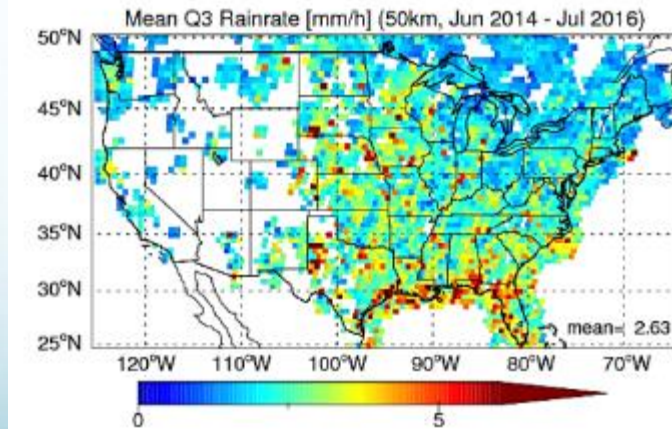
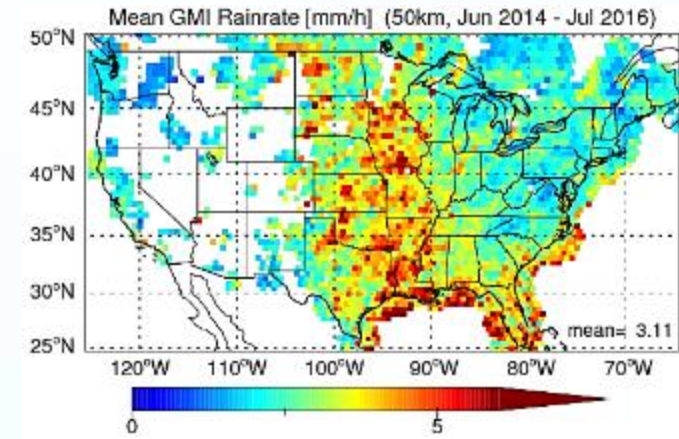
DPR



Combined



GPROF GMI

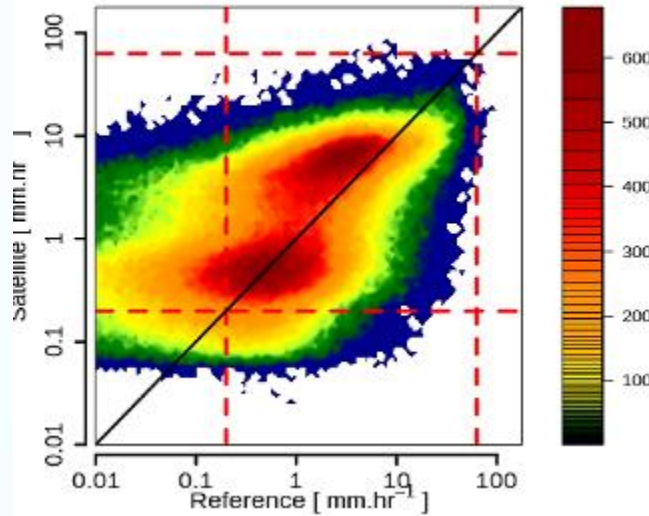


- Check to product to product variability- e.g., V5 DPR products all in good agreement with GV (similar to V4)
- Radar products in better agreement with MRMS; GPROF estimate in "MCS alley" still a little high.

V4 and V5 GPROF GMI, and L1 **Rain Rate** vs. GV MRMS

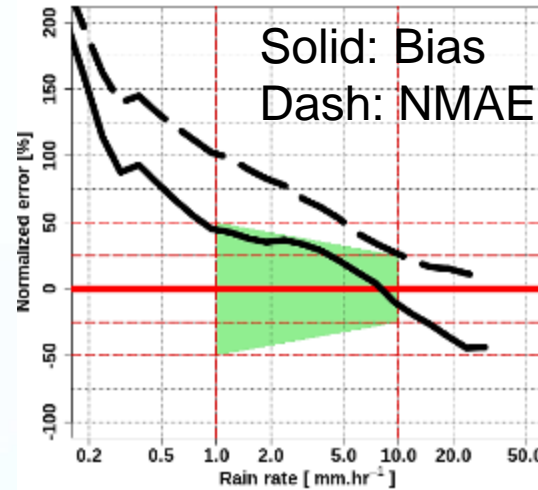
Footprint (15 km)

Satellite vs. Reference



V4

Level 1 (50 km)



V4

V4

Footprint:

Correlation 0.47, bias 24.6% - non-uniform and with modes;

L1:

Footprint:

Range of 0.2 - 60 mm/hr

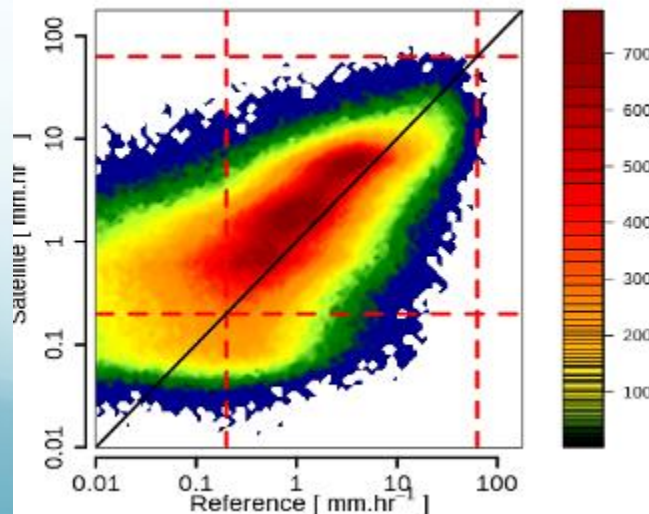
50 x 50 km

Bias

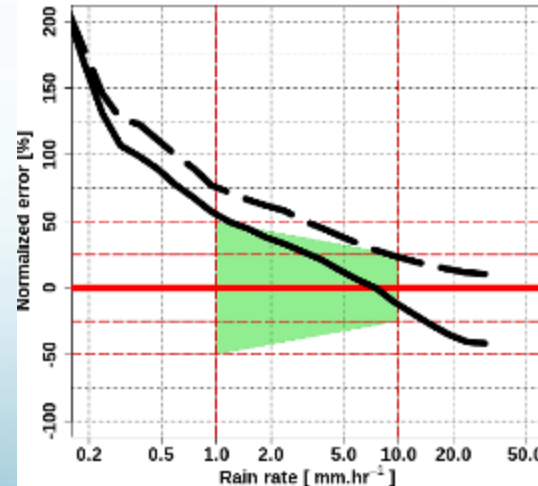
Random error (NMAE)



Satellite vs. Reference



V5



V5

V5

Footprint:

Correlation 0.57, bias 20 %;

Smoother bias, reduced NMAE;

greater extension to light rain;

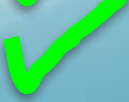
L1:

Footprint:

50x50km

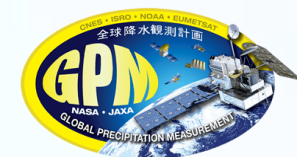
Bias: (better)

NMAE: (still a bit high)



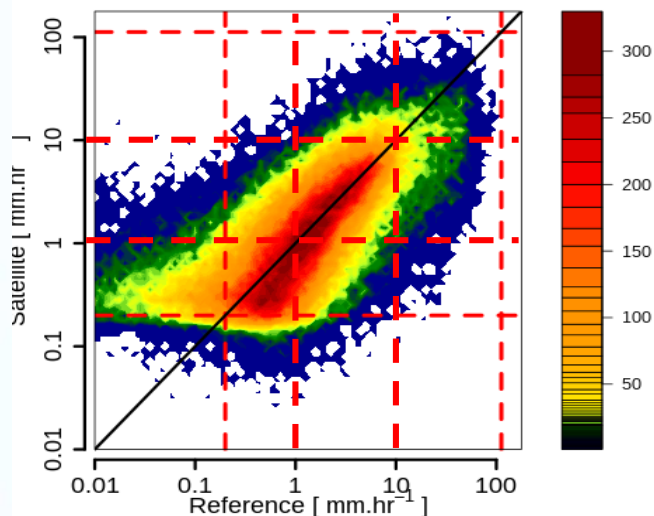


V4 and V5 **DPR MS**, and L1 **Rain Rate** vs. GV MRMS



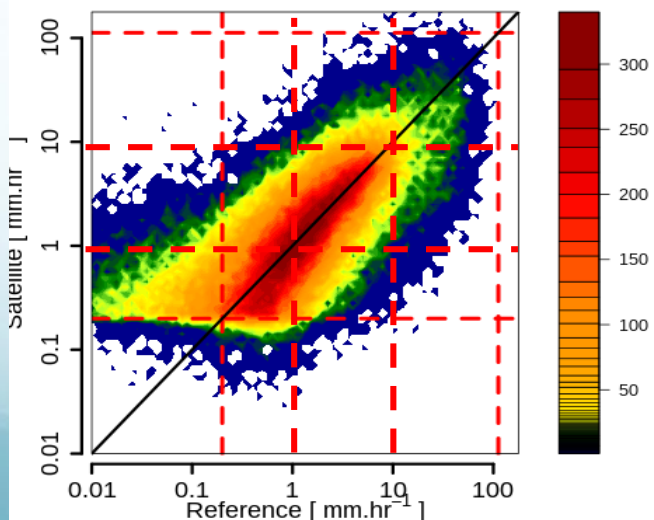
Footprint (~ 5 km)

Satellite vs. Reference



V4

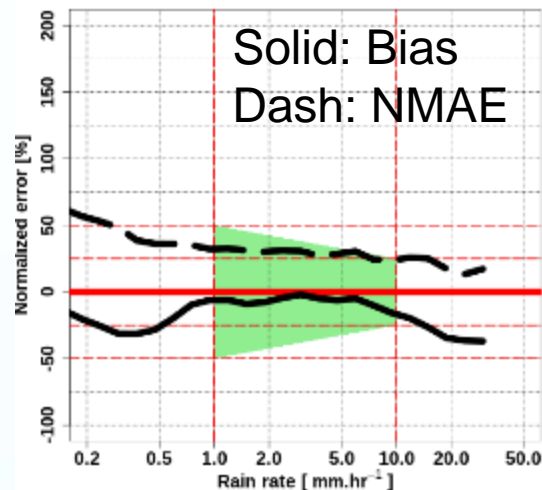
Satellite vs. Reference



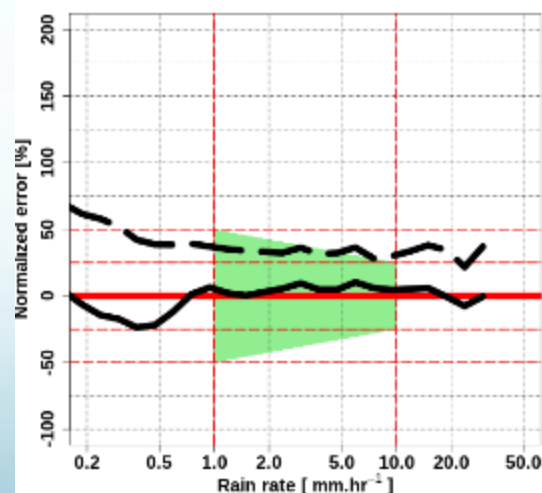
V5

Level 1 (50 km)

V4



V5



V4 ok, V5 better!

- V5 Conditional bias < 12%

L1:

Footprint:

0.2-110* mm/hr

(*sample numbers at >100 mm/hr; < 0.01%)



50 x 50 km

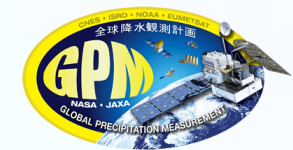
Bias

NMAE (improved V5)



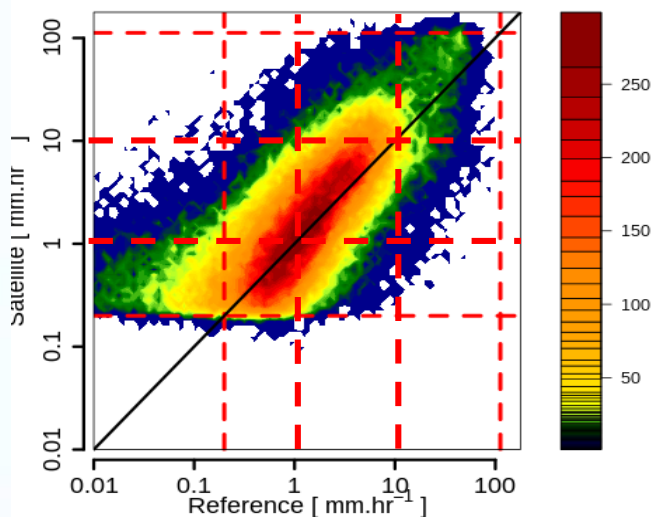


V4 and V5 Combined Alg. MS: Rain Rate vs. GV MRMS



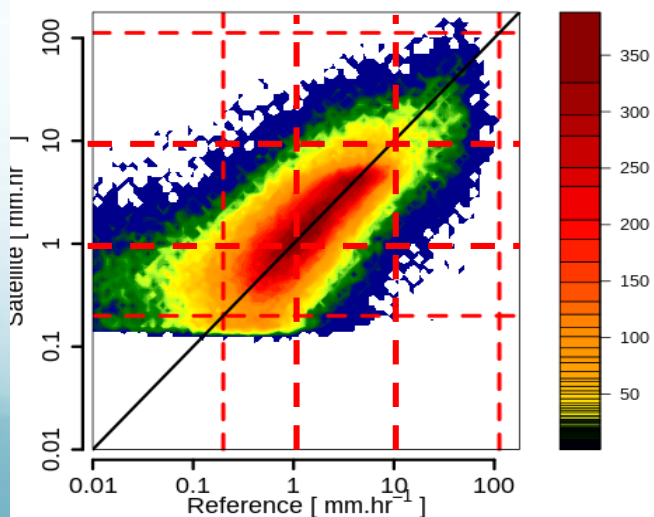
Footprint (~ 5 km)

Satellite vs. Reference



V4

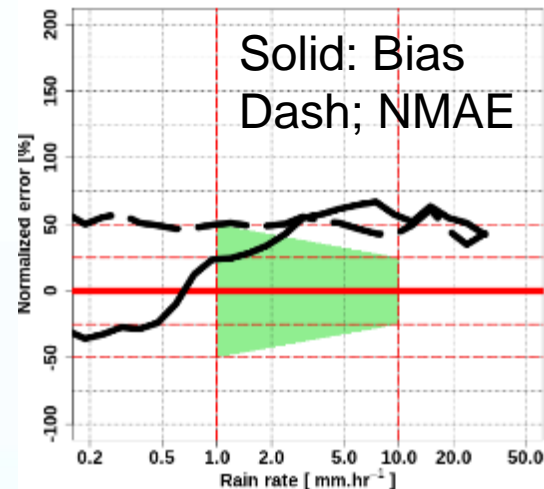
Satellite vs. Reference



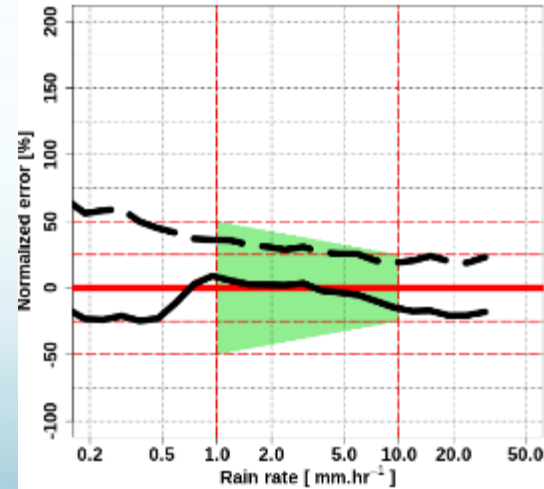
V5

Level 1 (50 km)

V4



V5



Relative to V4 (top; had known issues), V5 (bottom) is **MUCH** improved!

Conditional bias for V5 at footprint scale < 1% for V5

L1

Footprint:
0.2-110 mm/hr

50 x 50 km
Bias
NMAE





Ocean Radar (PAIH and KWAJ) Footprint (L1 proxy) Rain Rates V5

L1 requirements met (similar behavior to V4 with sporadic improvement)

Sensitivity to regime, beam filling and footprint size

CMB NS

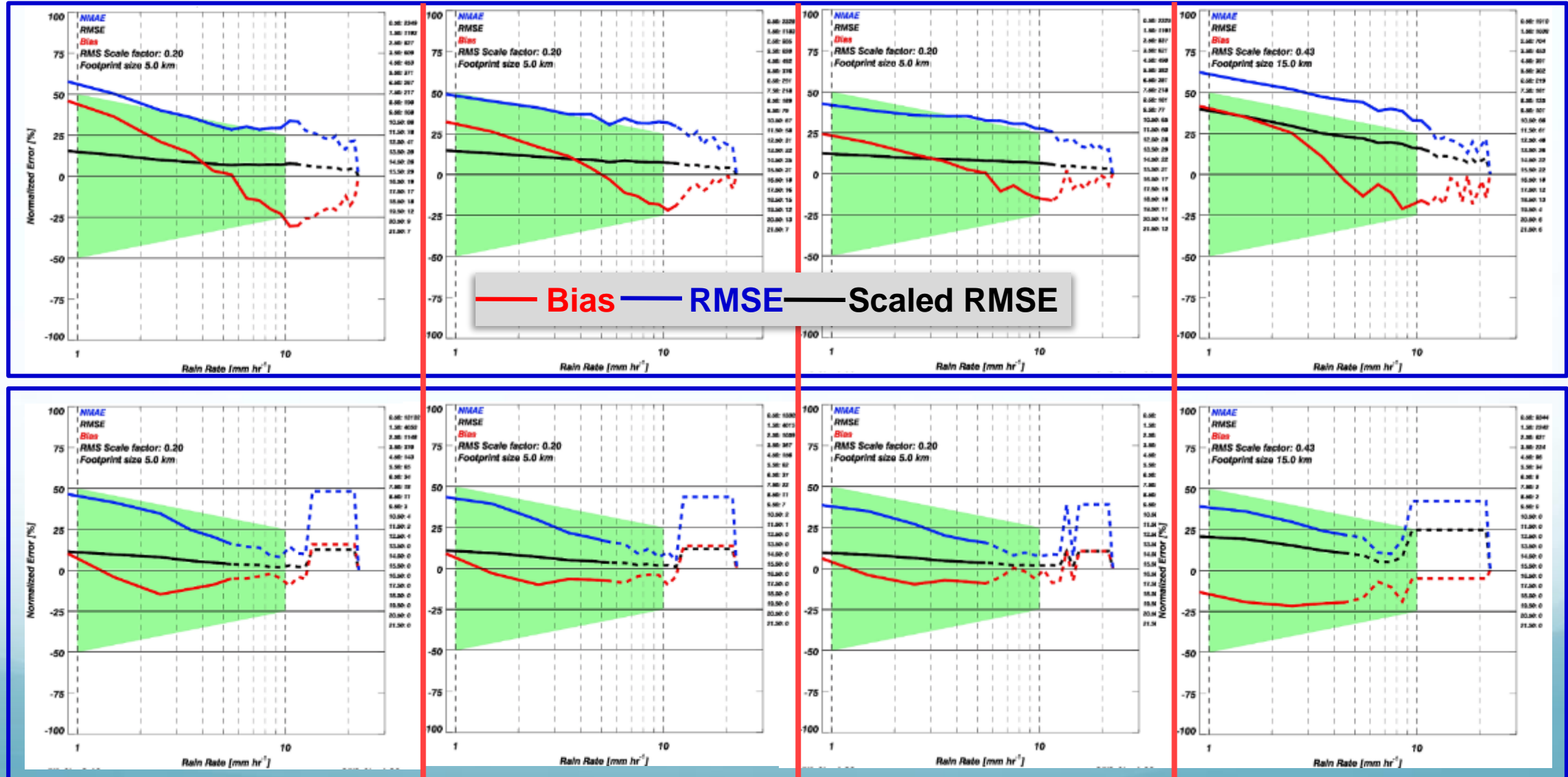
DPR NS

2AKu

GPROF-GMI

KWAJ
(8°N)

PAIH
(60° N)

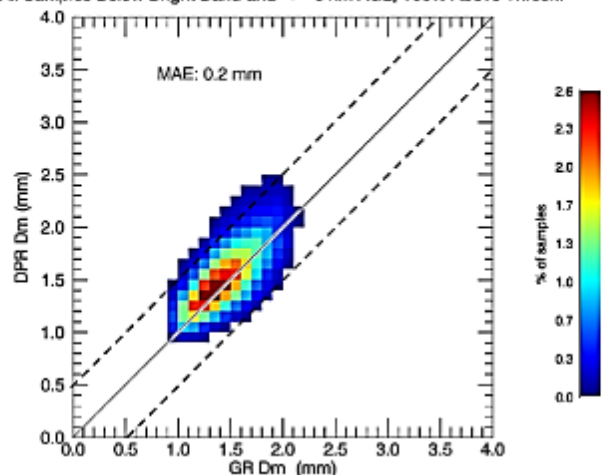


DPR MS V4, V5 vs. GV Radar D_m

V4

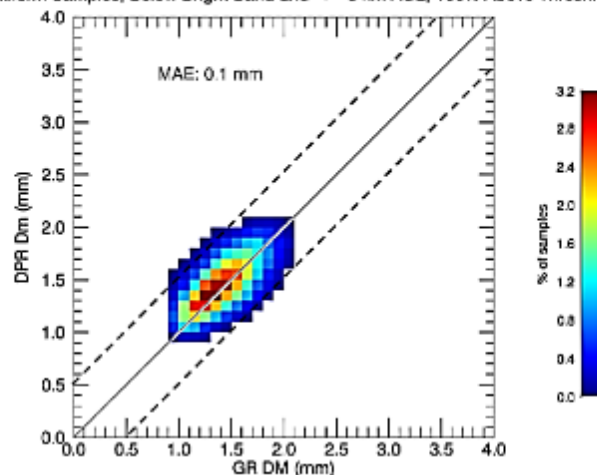
All Samples

2ADPR V04A D_m vs. GR D_m Scatter, Mean GR-DPR Bias: -0.1 mm, N=107274
All Samples Below Bright Band and ≤ 3 km AGL, 100% Above Threshold.



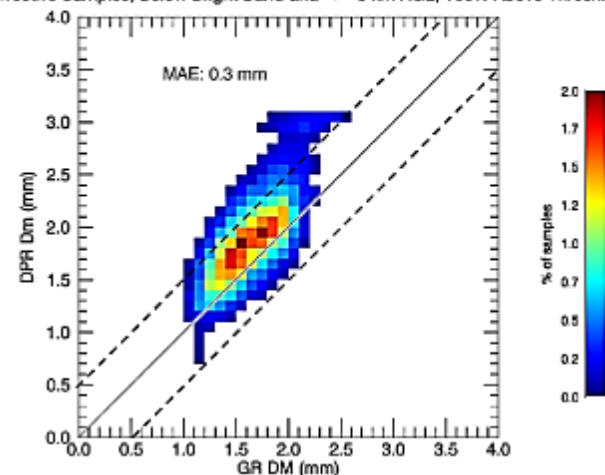
Stratiform

DPR V04A D_m vs. GR D_m Scatter, Mean GR-DPR Bias: -0.0 mm, N=82932
Stratiform Samples, Below Bright Band and ≤ 3 km AGL, 100% Above Threshold.



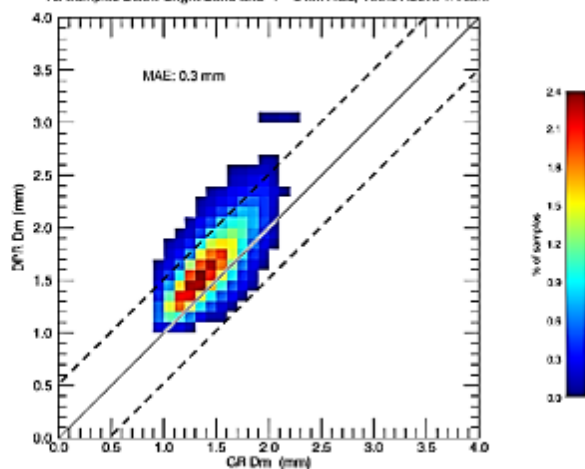
Convective

DPR V04A D_m vs. GR D_m Scatter, Mean GR-DPR Bias: -0.2 mm, N=24652
Convective Samples, Below Bright Band and ≤ 3 km AGL, 100% Above Threshold.

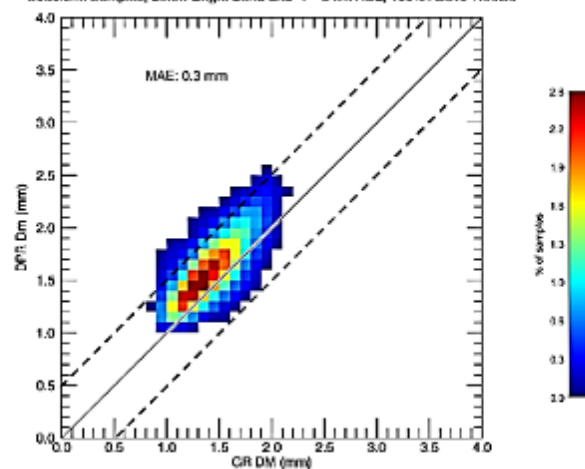


V5

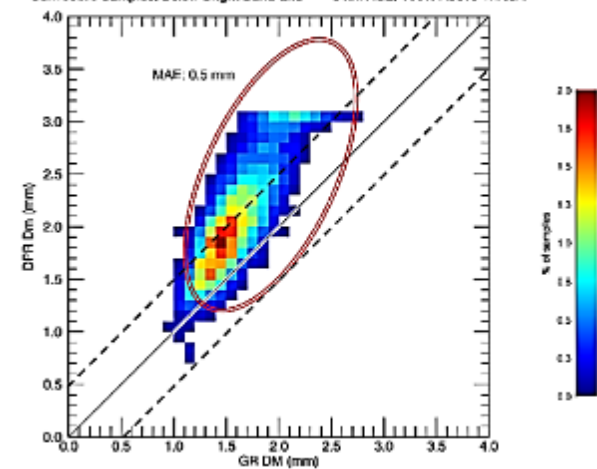
2ADPR V5 ITE114 D_m vs. GR D_m Scatter, Mean GR-DPR Bias: -0.3 mm, N=87143
All Samples Below Bright Band and ≤ 3 km AGL, 100% Above Threshold.



2ADPR V5 ITE114 D_m vs. GR D_m Scatter, Mean GR-DPR Bias: -0.2 mm, N=74247
Stratiform Samples, Below Bright Band and ≤ 3 km AGL, 100% Above Threshold.



2ADPR V5 ITE114 D_m vs. GR D_m Scatter, Mean GR-DPR Bias: -0.5 mm, N=12896
Convective Samples, Below Bright Band and ≤ 3 km AGL, 100% Above Threshold.



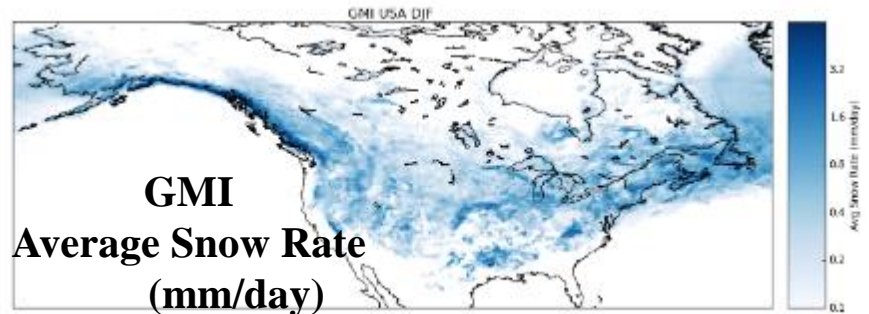
L1: Within limits...But..V5 Positive bias in D_m relative to GV; Convective deviates more from V4 (large D_m mode?) ✓



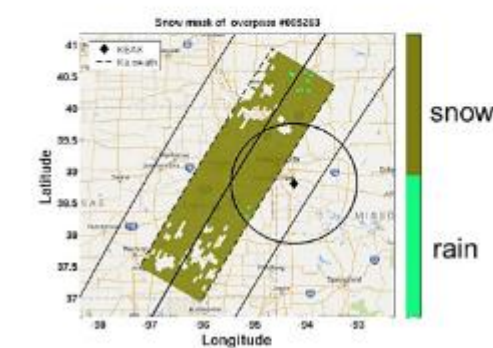
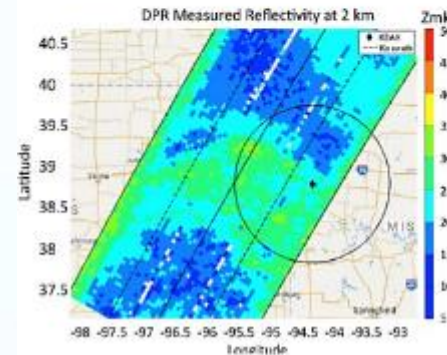
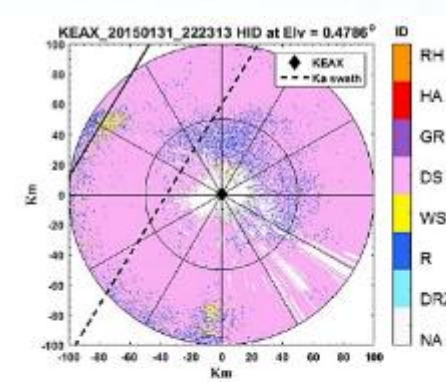
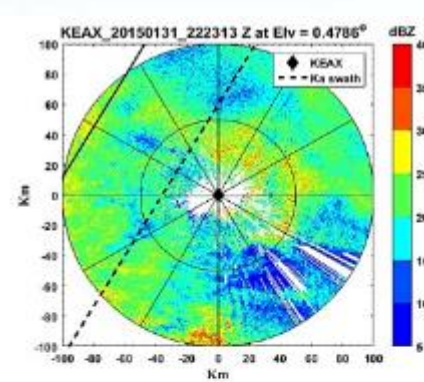
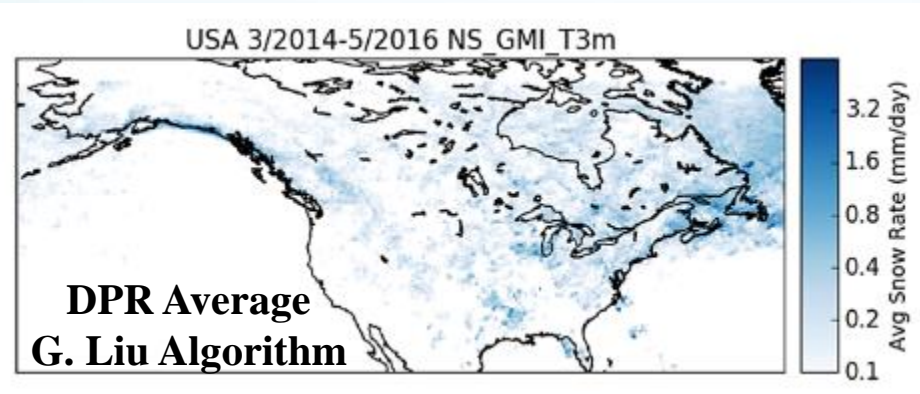
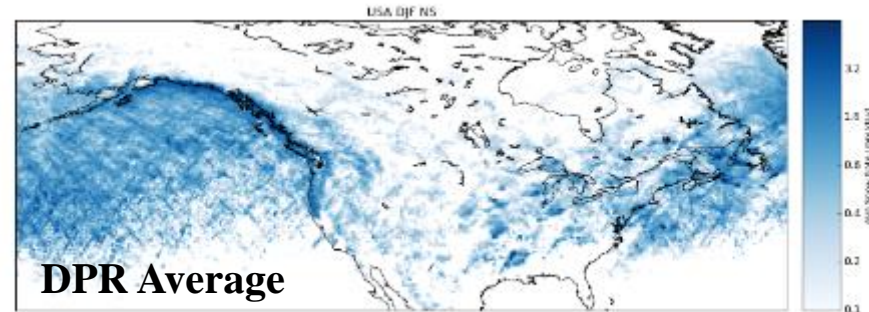
SNOW: “Demonstrate *Detection*”



GMI



DPR



Courtesy, V. Chandrasekar (CSU)

Version 5: New DFRm snow-Index (Le and Chandra):
Validation using 88D
HID algorithms
against DPR MS

This essentially demonstrates detection and satisfies requirements but.....difference in algorithms related to assignment of snow at/near the surface.



Quantifying Snow "Detection" and Rain-Snow "Delineation"



MRMS "reference" data. Heidke Skill Score (HSS) used to balance hits, misses, false alarms, correct rejects.

Delineation: MRMS determines "type" (rain or snow). HSS maximized against the reference type.

Detection: HSS maximized for the satellite as a function of MRMS snow water equivalent rate (SWER); the "detection" threshold then corresponds to the SWER at the inflection point of the HSS curve.

Product	Detection HSS / Threshold	Delineation HSS
GMI GPROF*	0.43 / 0.63 mm hr ⁻¹	0.77
DPR MS	0.49 / 0.58 mm hr ⁻¹	0.66
CMB MS	0.57 / 0.63 mm hr ⁻¹	0.67
DPR NS	0.43 / 0.58 mm hr ⁻¹	0.65
KuPR	0.44 / 0.58 mm hr ⁻¹	0.65

* Need to include snow/ice-covered surfaces when doing the statistics



- Detection threshold ~ 0.5 - 0.7 mm/hr for radar and radiometer consistent with theory and previous observational comparisons to gauges in U.S. (at least for radar)
- Radar product HSS for delineating rain/snow *at* the surface a bit lower than radiometer



Summary

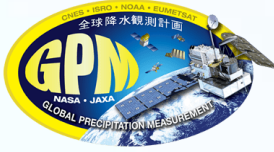


- GPM must meet "Level 1" science requirements for GPM Core Satellite products: footprint to 50 km scales, rain rate, DSD (hard requirement on D_m), and for demonstrating detection of snow.
- U.S. national network and research radar, disdrometer and gauge assets bridge point to satellite footprint scales, thus creating statistical validation datasets. Supplemental datasets (gauges, radars etc.) from other regions and international partners also used to help evaluate basic trends between products.
- ✓ L1 rain requirements demonstrated over the continental U.S. and two different ocean sites (tropical and high latitude) for GPM Version 4 and Version 5 products [exception GMI GPROF random error over continental U.S.].
- ✓ L1 DSD requirements satisfied for V4 and V5 algorithms. Shift in DSD behavior in V5 needs to be examined.
- ✓ L1 snow detection demonstrated and now expect stronger emphasis to be put on more robust estimation of SWER- possibly V6.
- GPM Version 5 products will be available by early May 2017 (see Erich Stocker, PPS, for details)

EXTRA



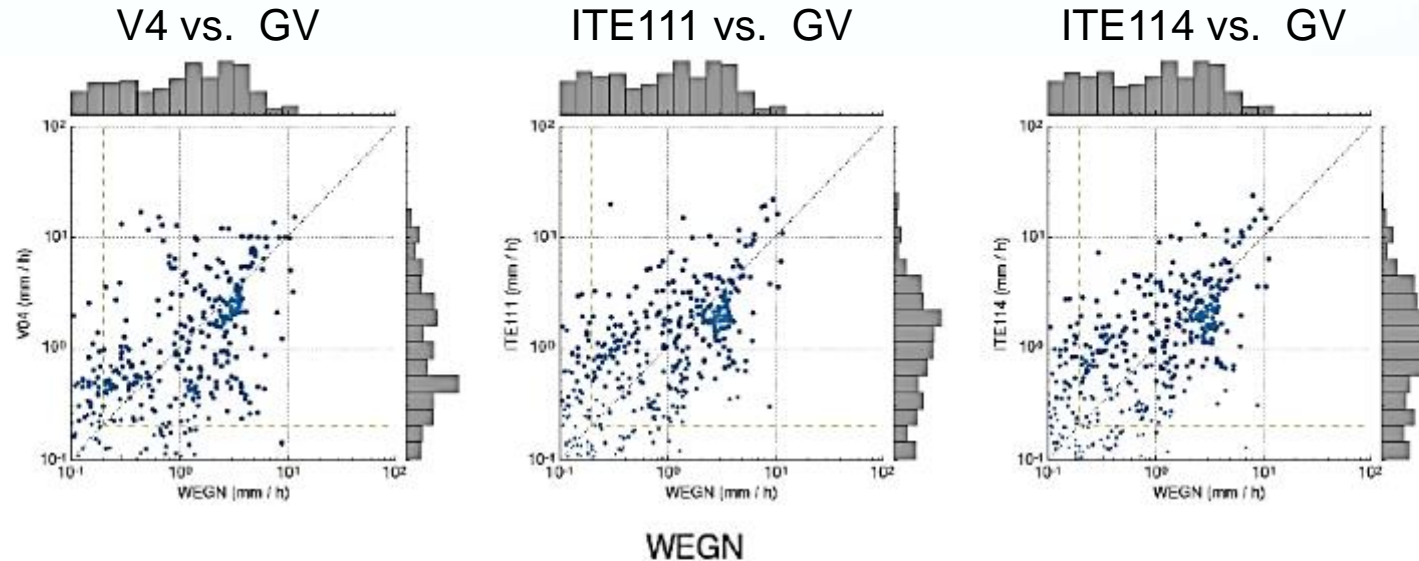
Rain Rate Footprints and Gauges: **GPROF GMI** V4 to ITE 114



1 Gauge every $\sim 1 \text{ km}^2$

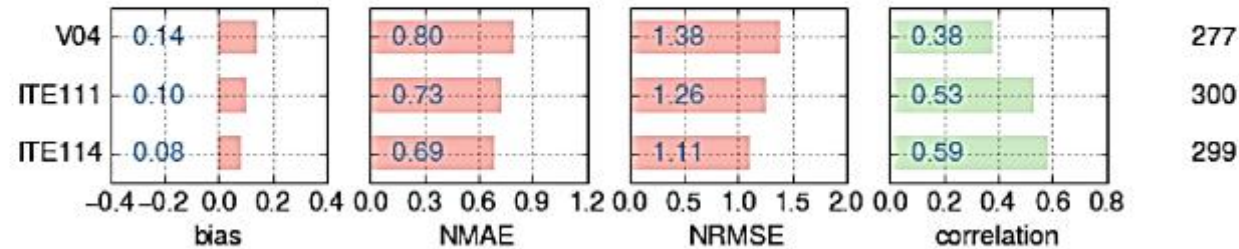
Require: Minimum 12-gauges/15 km footprint, 15 minute accumulation

Example:
WegenerNet, Austria



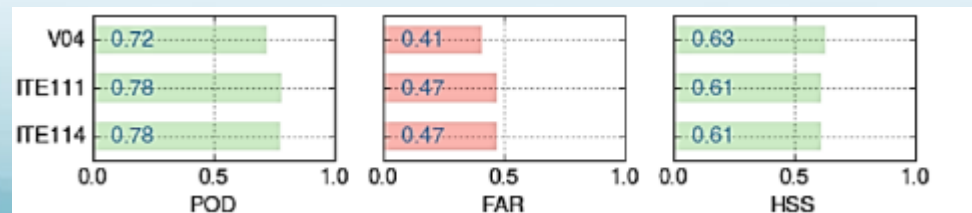
Good for tracking
steady improvements in
product.

Intensity

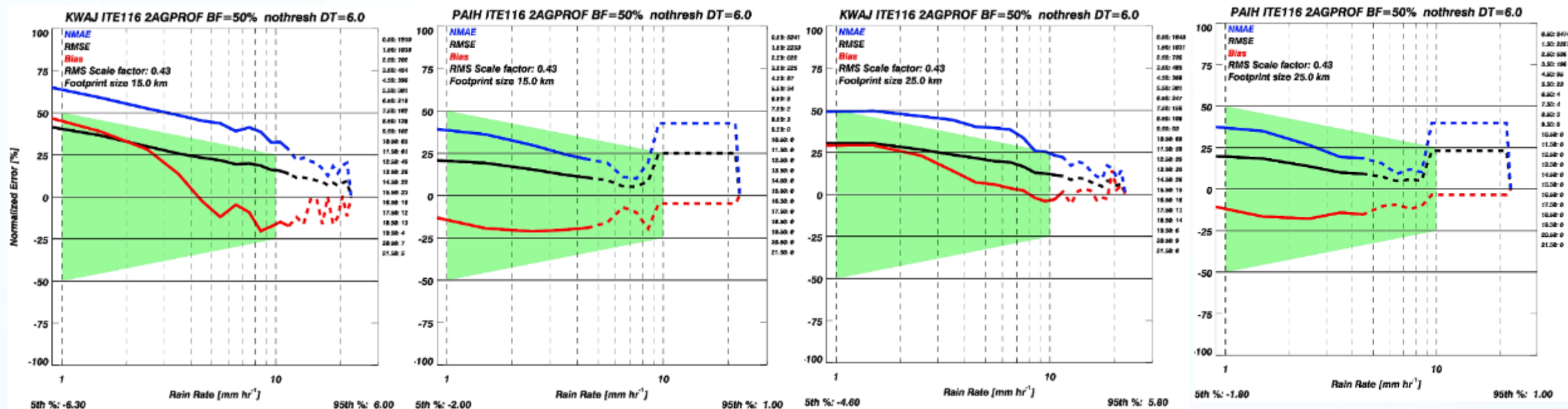


....but low sample
numbers at this stage
of the mission impact
scores.....

Detection

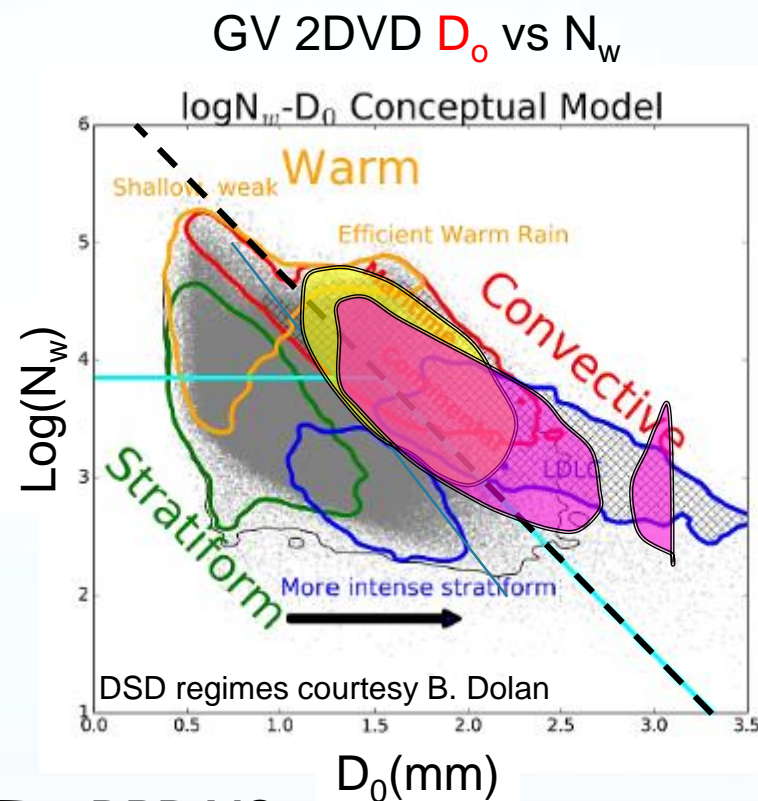
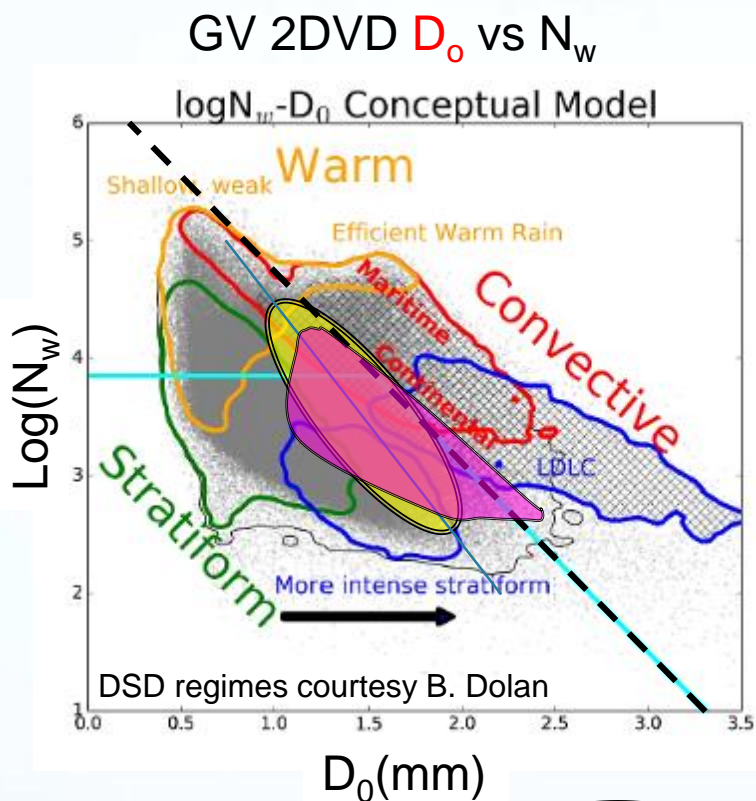


V5 GPROF GMI, and L1 Rain Rate vs. Ocean GV



Bias and Random error at 15 km footprint scale are within L1 over Ocean sites and generally improve by going to a 25 km footprint- more consistent with true "effective" footprint of algorithm over ocean.

DSD: V5 **DPR MS Convective** D_m and N_w



GV DPR MS

- DPR MS V5 fits GV sample space (Assuming $D_m \approx D_o$); behavior is somewhat similar to GPM GV Radar
- Shift to larger D_m and smaller N_w relative to GV; secondary mode at large D_m
- Combined algorithm (not shown) also generally "fits" GV - but with different N_w - D_m slope behavior in stratiform